

## **Legion Overview**

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## Logistics



#### Wireless

- Choose "Stanford Visitor" network, follow directions
- Bootcamp slides @ legion.stanford.edu

#### Thursday

- Extending the schedule by 15 minutes
- Parking
- Lunch
- Dinner
- Friday
  - Different building: Gates 505

### Team



- Alex Aiken
- Mike Bauer (Nvidia)
- Zhihao Jia
- Wonchan Lee
- Elliott Slaughter
- Sean Treichler

- Charles Ferenbaugh
- Sam Gutierrez
- Pat McCormick

## Legion



- A programming model for heterogeneous, distributed machines
- Heterogeneous
  - Mixed CPUs and GPUs
- Distributed
  - Large spread, and variability, of communication latencies
  - Caches, RAM, NUMA, network, …

## **One Slide History**



- Started in 2011
- First version in 2012
- S3D implementation in 2013
  - Collaboration with Jackie Chen's group at Sandia
  - Part of the ExaCT Center
  - Drove many feature changes/additions
  - And many optimizations/improvements

#### Emphasis on scaling up in 2014

S3D on 8,000 Titan nodes

#### **Legion S3D Heptane Performance**



1.73X - 2.85X faster between 1024 and 8192 nodes



December 4, 2014

### **Bootcamp Focus**



#### Writing Legion programs

- Different from the academic papers
- Cover many pragmatic, usability aspects
- This morning: The programming model
  - Tasks, regions, mapping

#### This afternoon: Everything else

- Structuring applications
- Debugging & profiling

#### Tomorrow: Working with application groups

## Philosophy



- Designed to be a real programming system
- Good abstractions, clear semantics
- But can also "open the hood"
  - Ways to drop down to lower-levels of abstraction
  - Within the programming model

## **Example Code**



```
for (t = 0; t < TIME\_STEPS; t++) {
  spawn (i = 0; i < MAX_PIECES; i++) calc_new_currents(pieces[i]);
  spawn (i = 0; i < MAX_PIECES; i++) distribute_charge(pieces[i], dt);
  spawn (i = 0; i < MAX_PIECES; i++) update_voltages(pieces[i]);
}
for (int i = 0; i < num_loops; i++)
Ł
 log_circuit(LEVEL_PRINT,"starting loop %d of %d", i, num_loops);
 // Calculate new currents
 runtime->execute_index_space(ctx, CALC_NEW_CURRENTS, task_space,
                              index_space_reqs, field_space_reqs, cnc_regions,
                              global_arg, local_args);
 // Distribute charge
```

#### // Update voltages

}

## **First Point**



```
for (t = 0; t < TIME_STEPS; t++) {
    spawn (i = 0; i < MAX_PIECES; i++) calc_new_currents(pieces[i]);
    spawn (i = 0; i < MAX_PIECES; i++) distribute_charge(pieces[i], dt);
    spawn (i = 0; i < MAX_PIECES; i++) update_voltages(pieces[i]);
}</pre>
```

#### Legion has a sequential semantics

- Easy to reason about
- But see discussion of advanced features this afternoon

#### Not like

- MPI
- OpenACC
- CUDA

## **Second Point**



#### A programming model

- embedded in C++
- but see discussion of future Legion compiler later today

```
for (int i = 0; i < num_loops; i++)</pre>
  log circuit(LEVEL PRINT,"starting loop %d of %d", i, num loops);
 // Calculate new currents
  runtime->execute_index_space(ctx, CALC_NEW_CURRENTS, task_space,
                                 index_space_reqs, field_space_reqs, cnc_regions,
                                global_arg, local_args);
 // Distribute charge
  runtime->execute_index_space(ctx, DISTRIBUTE_CHARGE, task_space,
                                 index_space_reqs, field_space_reqs, dsc_regions,
                                 global_arg, local_args);
 // Update voltages
  last = runtime->execute_index_space(ctx, UPDATE_VOLTAGES, task_space,
                                 index_space_regs, field_space_regs, upv_regions,
                                 global_arg, local_args);
}
```

## **Third Point**



#### A runtime system

- All decisions are made dynamically
- Again, see discussion of Legion compiler ...

```
for (int i = 0; i < num_loops; i++)
ł
  log_circuit(LEVEL_PRINT,"starting loop %d of %d", i, num loops);
 // Calculate new currents
  runtime->execute_index_space(ctx, CALC_NEW_CURRENTS, task_space,
                                index_space_reqs, field_space_reqs, cnc_regions,
                                global_arg, local_args);
 // Distribute charge
  runtime->execute_index_space(ctx, DISTRIBUTE_CHARGE, task_space,
                                index_space_reqs, field_space_reqs, dsc_regions,
                                global_arg, local_args);
 // Update voltages
  last = runtime->execute_index_space(ctx, UPDATE_VOLTAGES, task_space,
                                index_space_regs, field_space_regs, upv_regions,
                                global_arg, local_args);
```

}

#### Tasks



#### A task is

- The unit of parallel computation in Legion
- Takes regions (typed collections) as arguments
- Can launch subtasks

```
for (int i = 0; i < num_loops; i++)</pre>
  log_circuit(LEVEL_PRINT,"starting loop %d of %d", i, num_loops);
 // Calculate new currents
  runtime->execute_index_space(ctx, CALC_NEW_CURRENTS, task_space,
                                 index_space_regs, field_space_regs, cnc_regions,
                                 global arg, local args);
 // Distribute charge
  runtime->execute index space(ctx, DISTRIBUTE CHARGE, task space,
                                 index_space_reqs, field_space_reqs, dsc_regions,
                                 global_arg, local_args);
 // Update voltages
  last = runtime->execute_index_space(ctx, UPDATE_VOLTAGES, task_space,
                                 index_space_regs, field_space_regs, upv_regions,
                                 global arg, local args);
```

}







- Legion programs can launch arbitrary trees of tasks
- By default, execute in the order launched
- Runtime system automatically identifies parallel tasks

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## **Regions: Index & Field Spaces**



```
Circuit circuit;
Ł
  int num_circuit_nodes = num_pieces * nodes_per_piece;
  int num_circuit_wires = num_pieces * wires_per_piece;
 // Make index spaces
 IndexSpace node index space = runtime->create index space(ctx,num circuit nodes);
 IndexSpace wire index space = runtime->create index space(ctx,num circuit wires);
  // Make field spaces
  FieldSpace node field space = runtime->create field space(ctx);
  FieldSpace wire_field_space = runtime->create_field_space(ctx);
  FieldSpace locator_field_space = runtime->create_field_space(ctx);
 // Allocate fields
  circuit.node_field = allocate_field<CircuitNode>(ctx,runtime,node_field_space);
  circuit.wire_field = allocate_field<CircuitWire>(ctx,runtime,wire_field_space);
  circuit.locator_field = allocate_field<PointerLocation>(ctx,runtime,locator_field_space);
  // Make logical regions
  circuit.all_nodes = runtime->create_logical_region(ctx,node_index_space,node_field_space);
  circuit.all_wires = runtime->create_logical_region(ctx,wire_index_space,wire_field_space);
  circuit.node_locator = runtime->create_logical_region(ctx,node_index_space,locator_field_space);
}
         1
```



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## Regions



Two Dimensions Unbounded set of rows Bounded set of columns Fields Tasks declare Which fields they use And how they use them Regions can be partitioned

	Voltage	Capac.	Induct.	Charge
Node				

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### Partitioning



// first create the privacy partition that splits all the nodes into either shared or private
IndexPartition privacy\_part = runtime->create\_index\_partition(ctx, ckt.all\_nodes.get\_index\_space(), privacy\_map, true/\*disjoint\*/);

IndexSpace all\_private = runtime->get\_index\_subspace(ctx, privacy\_part, 0); IndexSpace all\_shared = runtime->get\_index\_subspace(ctx, privacy\_part, 1);





### Partitioning



// Now create partitions for each of the subregions

Partitions result; IndexPartition priv = runtime->create index partition(ctx, all private, private\_node\_map, true/\*disjoint\*/); result.pvt\_nodes = runtime->get\_logical\_partition\_by\_tree(ctx, priv, ckt.all\_nodes.get\_field\_space(), ckt.all\_nodes.get\_tree\_id()); IndexPartition shared = runtime->create\_index\_partition(ctx, all\_shared, shared\_node\_map, true/\*disjoint\*/); result.shr nodes = runtime->get logical partition by tree(ctx, shared, ckt.all nodes.get field space(), ckt.all nodes.get tree id()); IndexPartition ghost = runtime->create\_index\_partition(ctx, all\_shared, ghost\_node\_map, false/\*disjoint\*/); result.ghost\_nodes = runtime->get\_logical\_partition\_by\_tree(ctx, ghost, ckt.all\_nodes.get\_field\_space(), ckt.all\_nodes.get\_tree\_id());

IndexPartition pvt\_wires = runtime->create\_index\_partition(ctx, ckt.all\_wires.get\_index\_space(), wire\_owner\_map, true/\*disjoint\*/); result.pvt\_wires = runtime->get\_logical\_partition\_by\_tree(ctx, pvt\_wires, ckt.all\_wires.get\_field\_space(), ckt.all\_wires.get\_tree\_id());

IndexPartition locs = runtime->create\_index\_partition(ctx, ckt.node\_locator.get\_index\_space(), locator\_node\_map, true/\*disjoint\*/); result.node\_locations = runtime->get\_logical\_partition\_by\_tree(ctx, locs, ckt.node\_locator.get\_field\_space(), ckt.node\_locator.get\_tree\_id());



## **Organize Into Pieces**



```
// Build the pieces
for (int n = 0; n < num_pieces; n++)</pre>
Ł
  pieces[n].pvt_nodes = runtime->get_logical_subregion_by_color(ctx, result.pvt_nodes, n);
  pieces[n].shr_nodes = runtime->get_logical_subregion_by_color(ctx, result.shr_nodes, n);
  pieces[n].ghost_nodes = runtime->get_logical_subregion_by_color(ctx, result.ghost_nodes, n);
  pieces[n].pvt_wires = runtime->get_logical_subregion_by_color(ctx, result.pvt_wires, n);
  pieces[n].num_wires = wires_per_piece;
  pieces[n].first_wire = first_wires[n];
  pieces[n].num_nodes = nodes_per_piece;
  pieces[n].first_node = first_nodes[n];
  pieces[n].dt = DELTAT;
  pieces[n].steps = steps;
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                                                                           S
                                               p<sub>n</sub>
                                                                                               19
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                                        http://legion.stanford.edu
```

## **Embedded in C++**



```
// Build the pieces
for (int n = 0; n < num_pieces; n++)
{
    pieces[n].pvt_nodes = runtime->get_logical_subregion_by_color(ctx, result.pvt_nodes, n);
    pieces[n].shr_nodes = runtime->get_logical_subregion_by_color(ctx, result.shr_nodes, n);
    pieces[n].ghost_nodes = runtime->get_logical_subregion_by_color(ctx, result.ghost_nodes, n);
    pieces[n].pvt_wires = runtime->get_logical_subregion_by_color(ctx, result.pvt_wires, n);
    pieces[n].num_wires = wires_per_piece;
    pieces[n].first_wire = first_wires[n];
    pieces[n].num_nodes = nodes_per_piece;
    pieces[n].first_node = first_nodes[n];
    pieces[n].dt = DELTAT;
    pieces[n].steps = steps;
}
```

#### Can write any C++ code within a task

- Local state, pointers, etc.
- Must follow discipline when using Legion API

#### Regions are first class

Can be passed as arguments, stored in data structures

## **Populating Regions**



# Can't read/update a region without an *instance* Instances hold a valid current copy of the data

```
{
```

```
log_circuit(LEVEL_PRINT,"Initializing circuit simulation...");
// inline map physical instances for the nodes and wire regions
RegionRequirement wires_req(ckt.all_wires, READ_WRITE, EXCLUSIVE, ckt.all_wires);
wires_req.add_field(ckt.wire_field);
RegionRequirement nodes_req(ckt.all_nodes, READ_WRITE, EXCLUSIVE, ckt.all_nodes);
nodes_req.add_field(ckt.node_field);
RegionRequirement locator_req(ckt.node_locator, READ_WRITE, EXCLUSIVE, ckt.node_locator);
locator_req.add_field(ckt.locator_field);
PhysicalRegion wires = runtime->map_region(ctx, wires_req);
PhysicalRegion nodes = runtime->map_region(ctx, nodes_req);
```

PhysicalRegion locator = runtime->map\_region(ctx, locator\_req);

## **Populating Regions**



#### To read/update a region, need an accessor

A handle to reference, or iterate through, elements

```
nodes.wait_until_valid();
RegionAccessor<AccessorType::Generic, CircuitNode> nodes_acc = nodes.get_accessor().typeify<CircuitNode>();
locator.wait_until_valid();
RegionAccessor<AccessorType::Generic, PointerLocation> locator_acc = locator.get_accessor().typeify<PointerLocation>();
ptr t *first nodes = new ptr t[num pieces];
Ł
  IndexAllocator node_allocator = runtime->create_index_allocator(ctx, ckt.all_nodes.get_index_space());
  node_allocator.alloc(num_pieces * nodes_per_piece);
}
{
  IndexIterator itr(ckt.all_nodes.get_index_space());
  for (int n = 0; n < num_pieces; n++)</pre>
  {
    for (int i = 0; i < nodes_per_piece; i++)</pre>
    ł
      assert(itr.has_next());
      ptr_t node_ptr = itr.next();
      if (i == 0)
        first_nodes[n] = node_ptr;
      CircuitNode node;
      node.charge = 0.f;
      node.voltage = 2*drand48() - 1;
      node.capacitance = drand48() + 1;
      node.leakage = 0.1f * drand48();
```

## **Regions: Privileges & Coherence**



```
void calc_new_currents(CircuitPiece piece):
       RWE(piece.rw_pvt), ROE(piece.rn_pvt, piece.rn_shr, piece.rn_ghost) {
 foreach(w : piece.rw_pvt)
   w \rightarrow current = (w \rightarrow in\_node \rightarrow voltage - w \rightarrow out\_node \rightarrow voltage) / w \rightarrow resistance;
}
// Build the region requirements for each task
std::vector<RegionReguirement> cnc_regions;
cnc_regions.push_back(RegionRequirement(parts.pvt_wires, 0/*identity colorize function*/,
                       READ WRITE, EXCLUSIVE, circuit.all wires));
cnc_regions.back().add_field(circuit.wire_field);
cnc regions.push back(RegionReguirement(parts.pvt nodes, 0/*identity*/,
                       READ_ONLY, EXCLUSIVE, circuit.all_nodes));
cnc_regions.back().add_field(circuit.node field);
cnc_regions.push_back(RegionRequirement(parts.shr_nodes, 0/*identity*/,
                       READ_ONLY, EXCLUSIVE, circuit.all_nodes));
cnc_regions.back().add_field(circuit.node_field);
cnc_regions.push_back(RegionRequirement(parts.ghost_nodes, 0/*identity*/,
                       READ_ONLY, EXCLUSIVE, circuit.all_nodes));
cnc_regions.back().add_field(circuit.node_field);
```

### **Back to the Simulation**





### The Crux



- Crucial design decisions in a Legion program are:
- What are the regions?
  - How are the regions partitioned into subregions?
- What are the tasks?
  - How are the tasks decomposed into subtasks?
- Often tension between the two
  - These decisions drive the program's design

## Summary



#### The programmer

- Describes the structure of the program's data
  - Regions
- The tasks that operate on that data
- The Legion implementation
  - Guarantees tasks appear to execute in sequential order
  - Ensures tasks have valid versions of their regions

## **Mapping Interface**

Programmer selects:

- Mapping computed dynamically
- **Decouple correctness from** 0 performance





## Mapping



```
Processor CircuitMapper::select_target_processor(const Task *task)
{
    if (task->task_id == REGION_MAIN)
        return local_proc;
    // All other tasks get mapped onto the GPU
    assert(task->is_index_space);
    DomainPoint point = task->index_point;
    unsigned proc_id = point.get_index() % gpu_procs.size();
    return gpu_procs[proc_id];
}
```

#### Mapper interface = callback interface

- Legion runtime calls user-supplied methods
- Can do arbitrary computation to make decisions
   But often very simple

## The Crux, Revisited



- Crucial design decisions in a Legion program are
  - What are the regions?
  - What are the tasks?

- In particular, mapping decisions depend on design of the regions and tasks
  - Not the other way around

## Debugging









## **Questions?**